

(MM, A) LIMEPY

(Multi-Mass, Anisotropic) Lowered Isothermal Model Explorer in PYthon

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ArXiv:1508.02120

<https://github.com/mgieles/limepy>



Motivation

Model

Applications

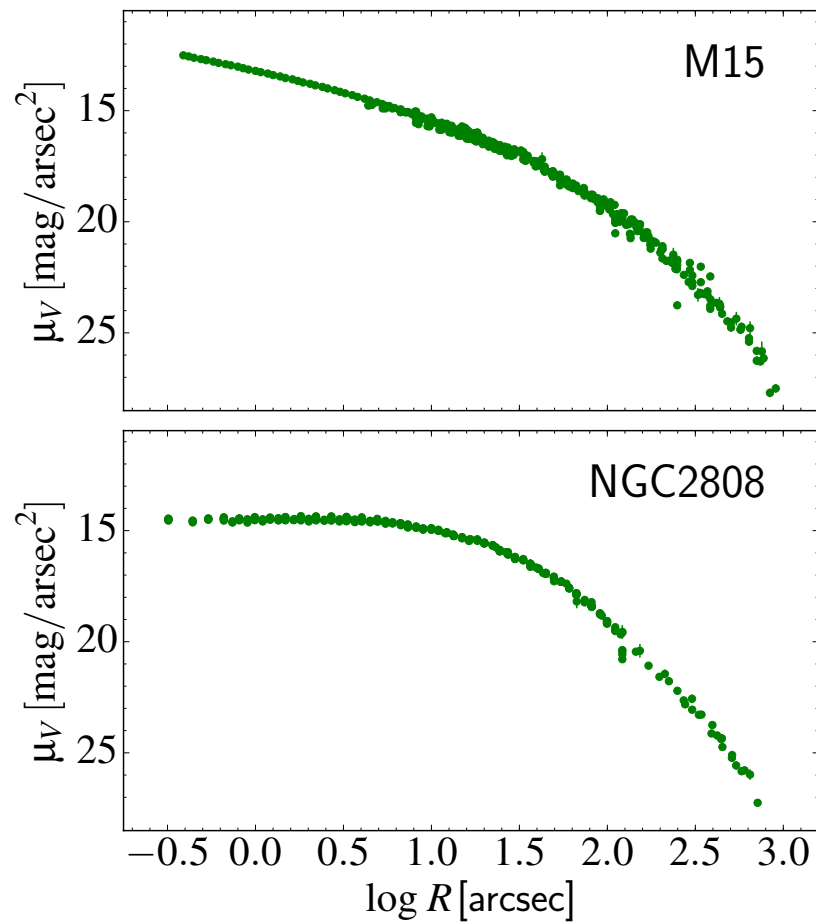
Installing

Running

Plotting

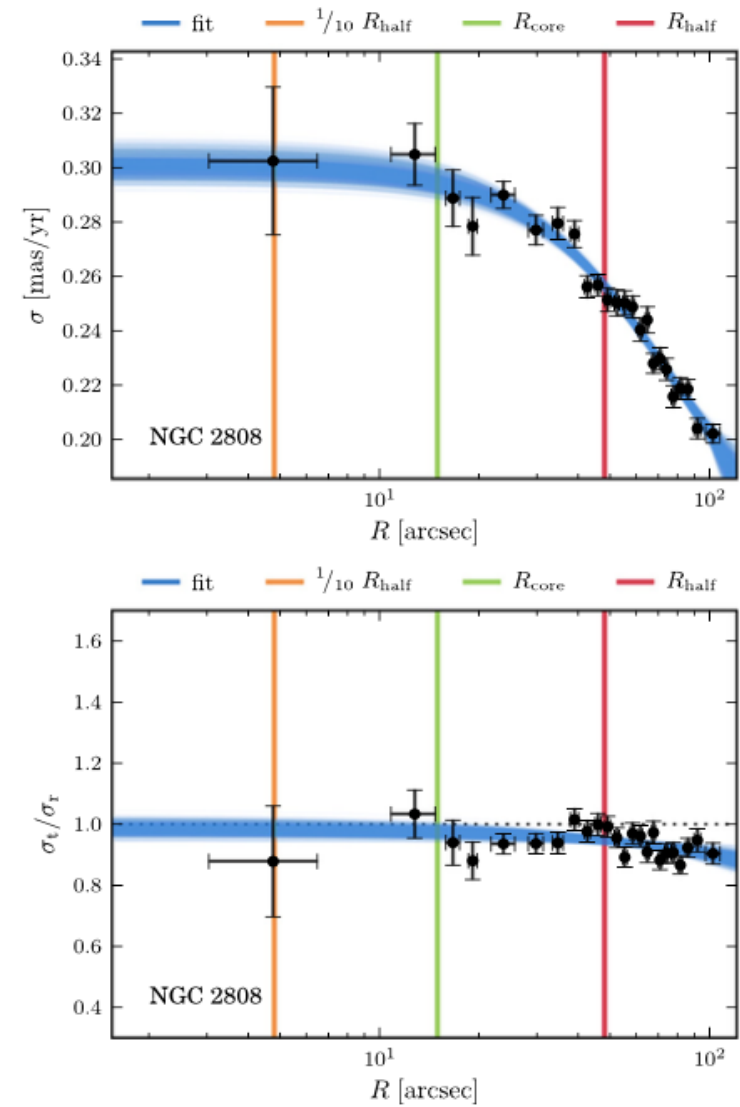
Motivation

Surface brightness



Trager, King & Djorgovski (1995)

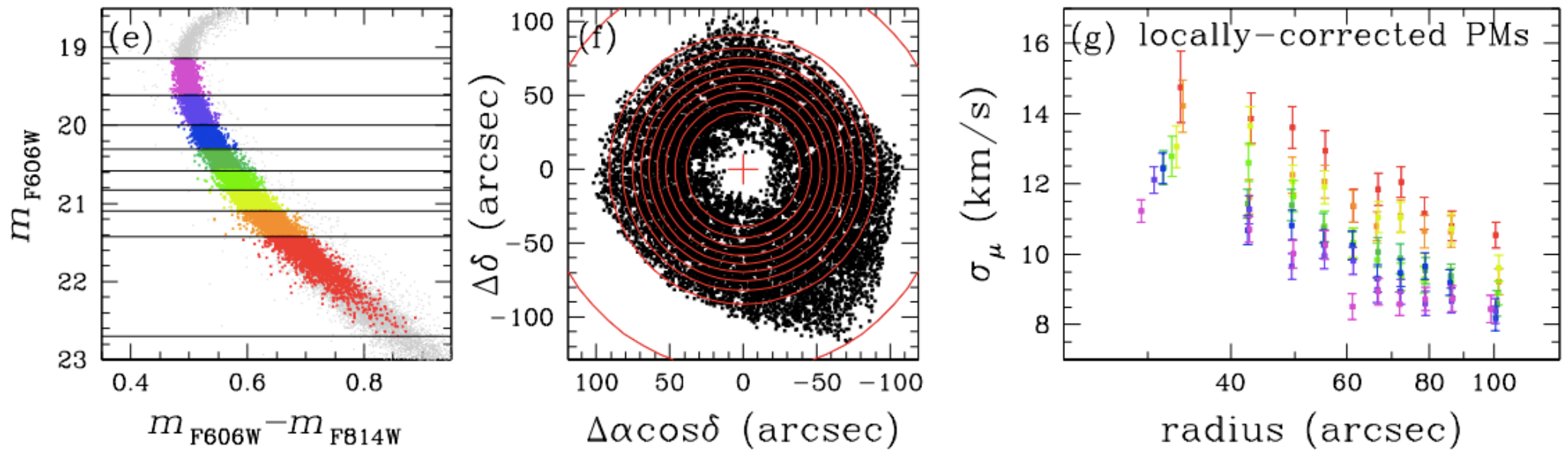
HST proper motions



Watkins+ (2015)

Motivation

Luminosity/mass dependent kinematics

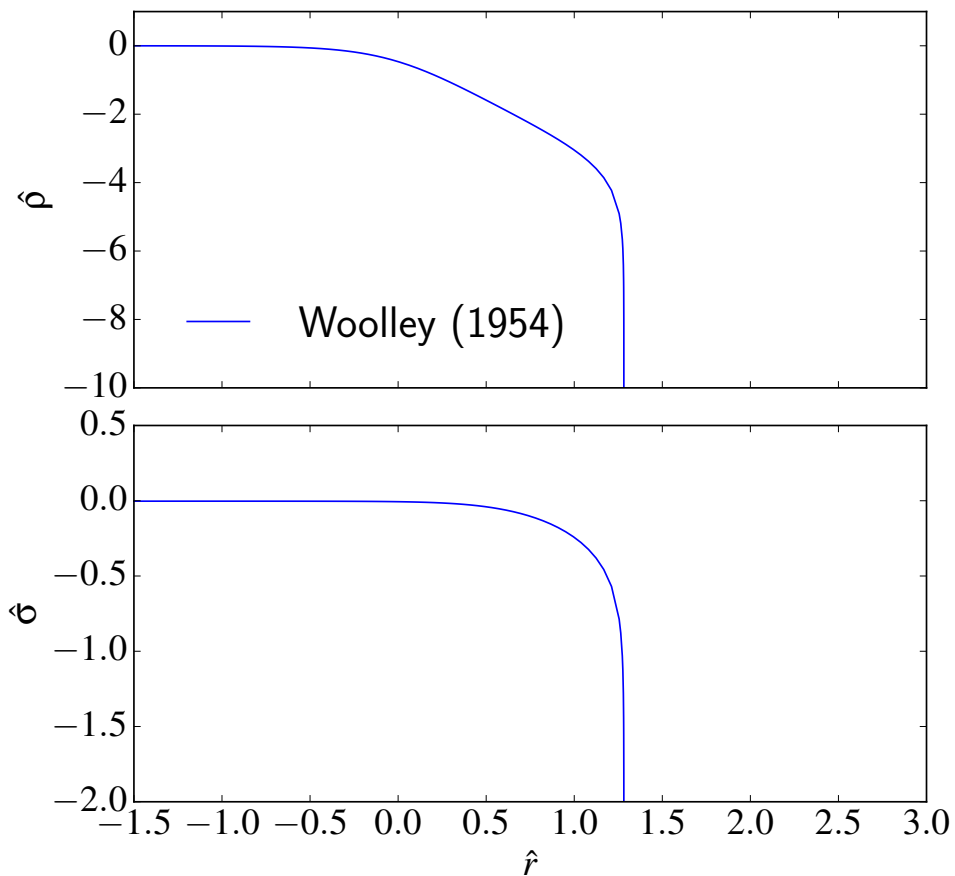


M15: Bellini+ (2014)

Lowered isothermal models

Simple truncation

Woolley (1954)



$$f(\hat{E}) = A \exp(\hat{E})$$

$$\hat{E} = \frac{\phi(r_t) - E}{s^2}$$

E = specific energy

$\phi(r_t)$ = specific potential at r_t

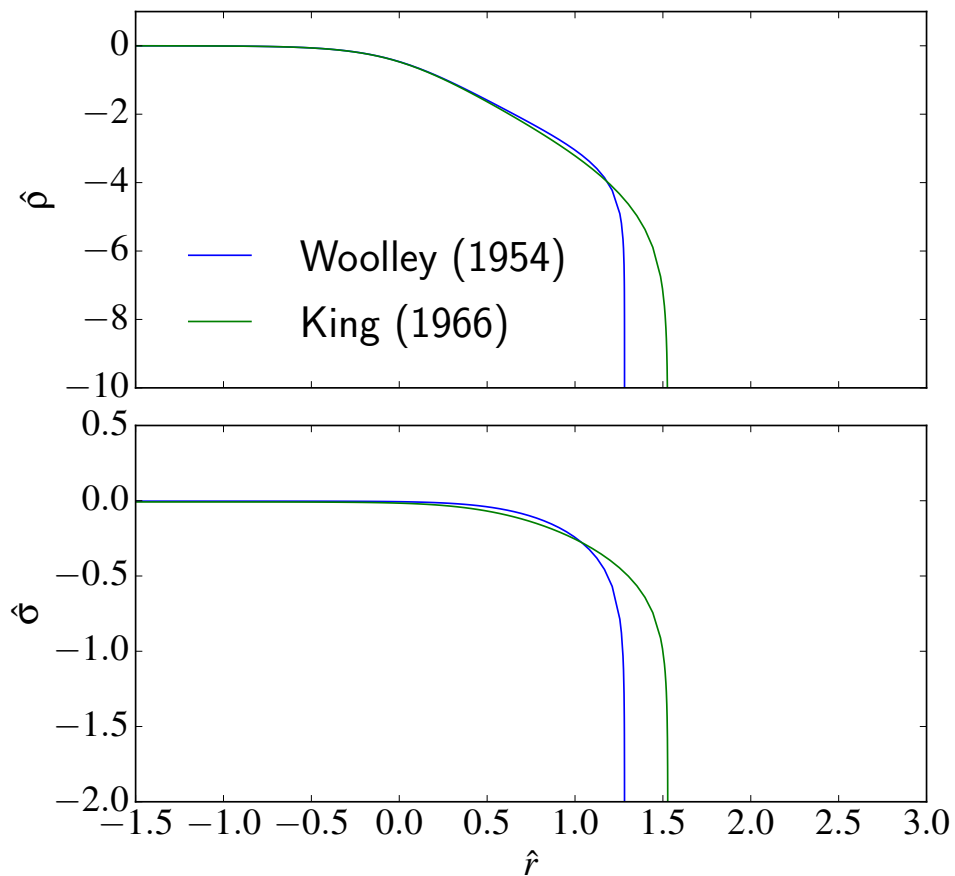
s = velocity scale

Lowered isothermal models

Simple truncation + continuous DF

Michie (1963); King (1966)

$$f(\hat{E}) = A \left[\exp(\hat{E}) - 1 \right]$$



$$\hat{E} = \frac{\phi(r_t) - E}{s^2}$$

E = specific energy

$\phi(r_t)$ = specific potential at r_t

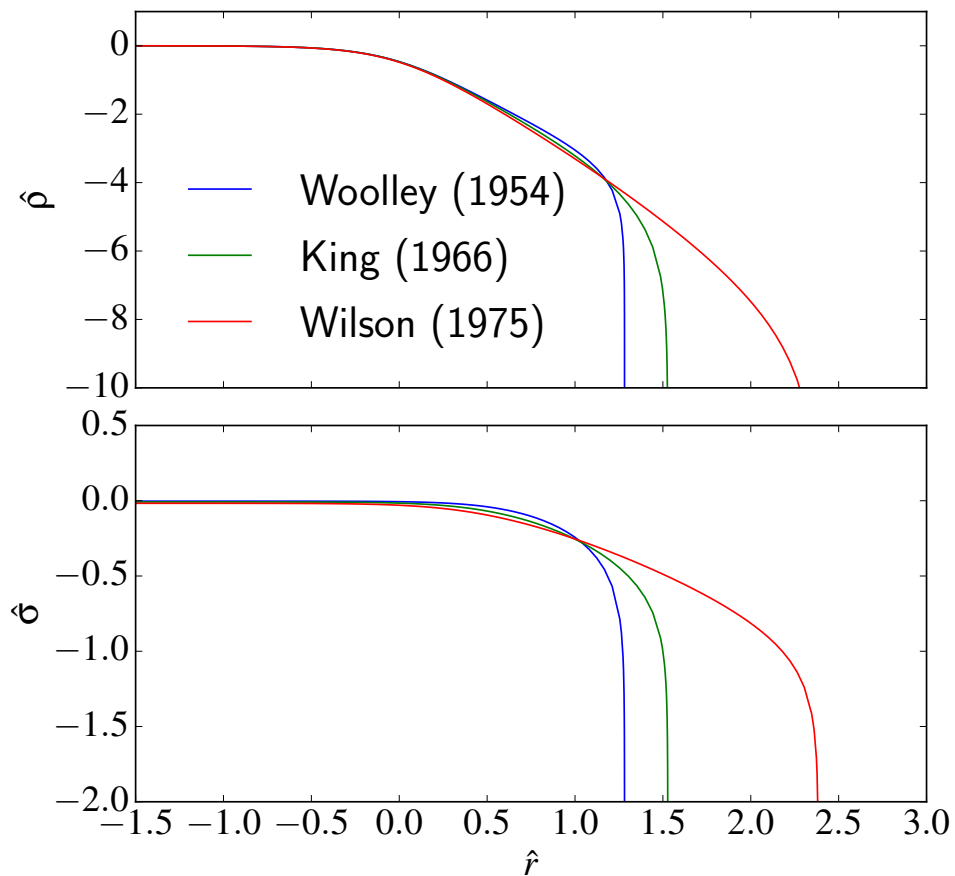
s = velocity scale

Lowered isothermal models

Simple truncation + continuous DF & DF'

Wilson (1975)

$$f(\hat{E}) = A \left[\exp(\hat{E}) - 1 - \hat{E} \right]$$



$$\hat{E} = \frac{\phi(r_t) - E}{s^2}$$

E = specific energy

$\phi(r_t)$ = specific potential at r_t

s = velocity scale

Lowered isothermal models

$$f(n, \hat{E}) = \begin{cases} A \exp(\hat{E}), & n = 0 \\ A \left[\exp(\hat{E}) - \sum_{i=0}^{n-1} \frac{\hat{E}^i}{i!} \right], & n > 0 \end{cases}$$

Davoust (1977)

$$f(g, \hat{E}) = AE_\gamma(g, \hat{E}) \quad E_\gamma(g, \hat{E}) = \begin{cases} \exp(\hat{E}), & g = 0 \\ \exp(\hat{E}) \frac{\gamma(g, \hat{E})}{\Gamma(g)}, & g > 0 \end{cases}$$

Gomez-Leyton & Valezquez (2014)

LIMEPY

$$f = A \exp(-\hat{J}^2) E_\gamma(g, \hat{E})$$

3 parameters: $\hat{\phi}_0, g, r_a$

2 scales: A, s

$$\hat{E} = \frac{\phi(r_t) - E}{s^2}$$

$$\hat{J}^2 = \frac{r^2 v_t^2}{2s^2 r_a^2}$$

Multi-mass LIMEPY

Include mass dependence in f in a self-consistent way

$$\nabla^2 \phi = 4\pi G \sum_j \int f_j d^3 v$$

Da Costa & Freeman 1976; Gunn & Griffin 1979

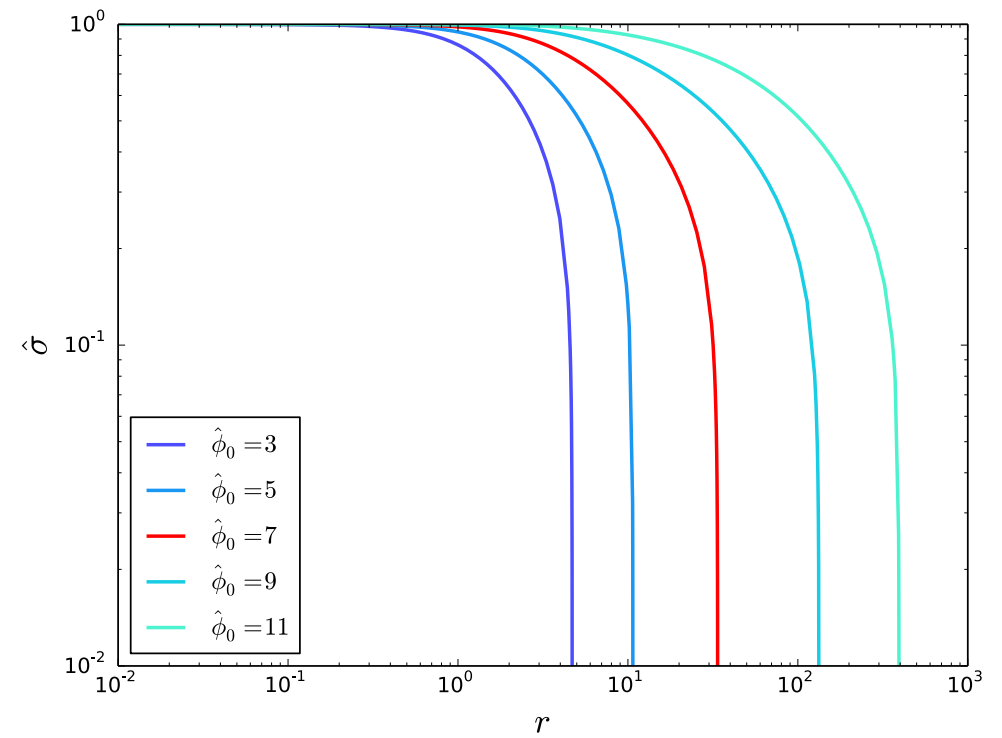
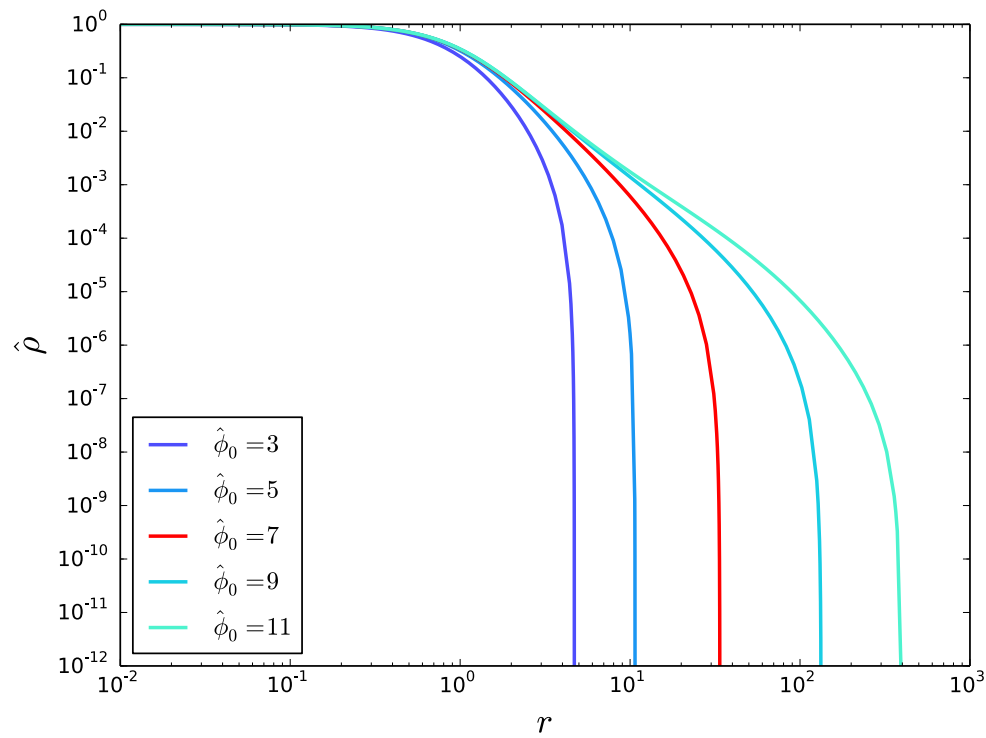
$$s_j = s \left(\frac{m_j}{\bar{m}} \right)^{-\delta} \quad r_{a,j} = r_a \left(\frac{m_j}{\bar{m}} \right)^{\eta}$$

$2N_{\text{bin}} + 2$ additional parameter: m_j, M_j, δ, η

LIMEPY

Some properties of the models: the role of $\hat{\phi}_0$

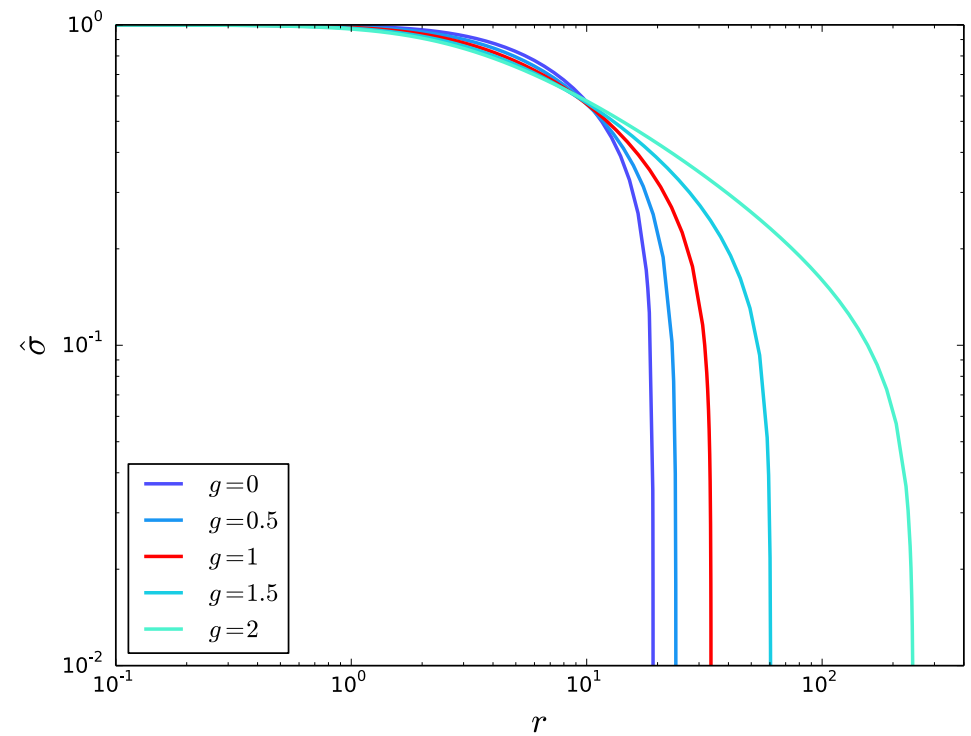
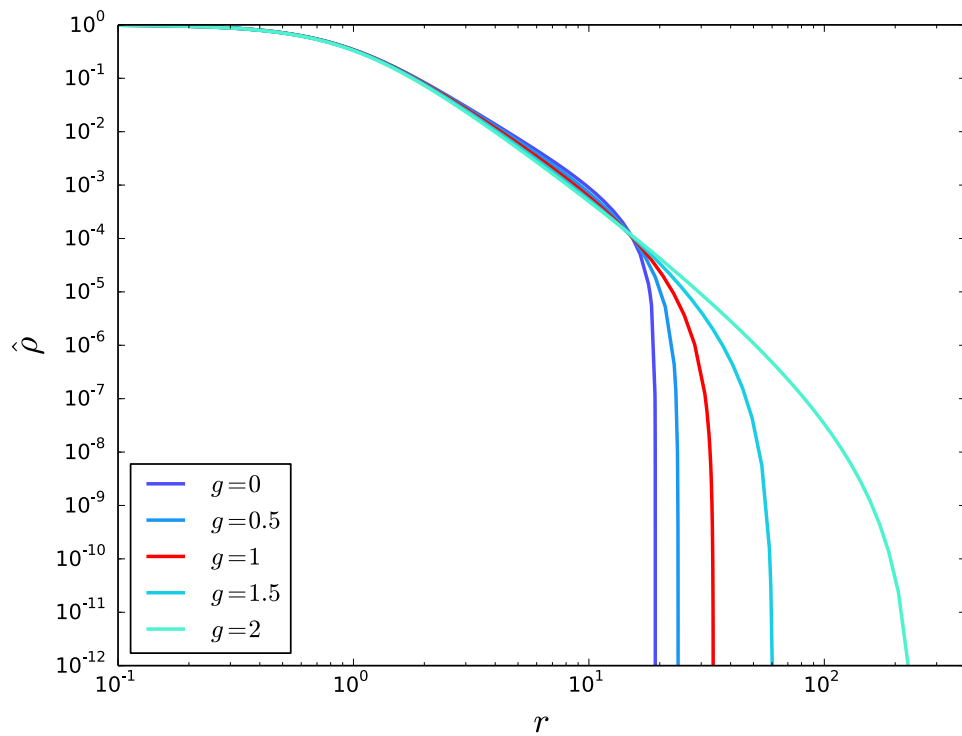
$$g = 1, r_a \rightarrow \infty$$



LIMEPY

Some properties of the models: the role of g

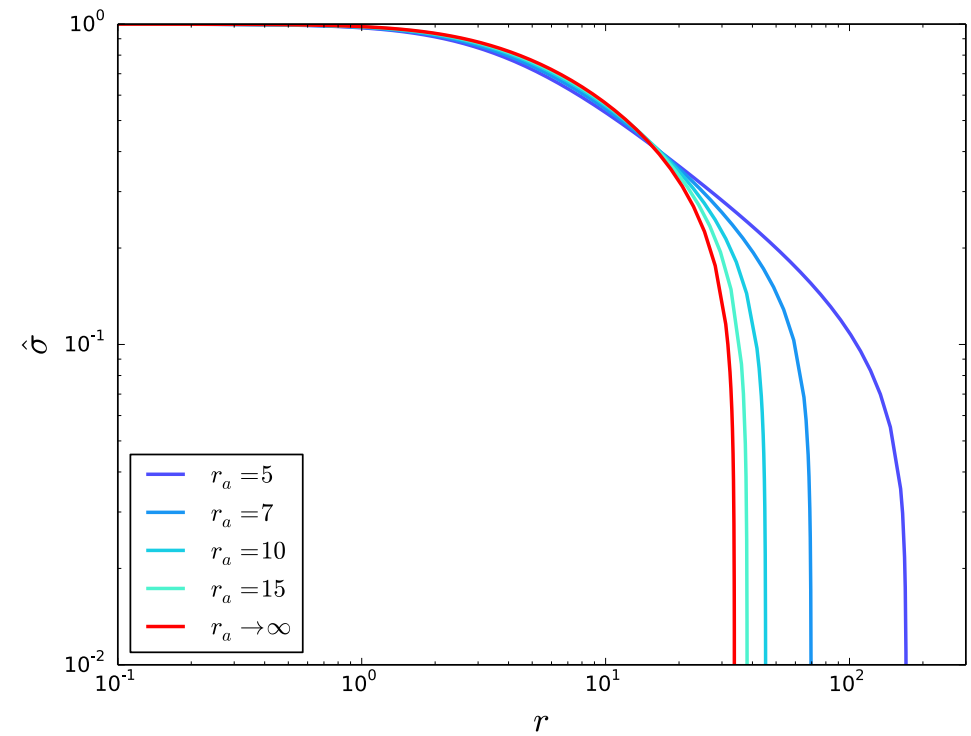
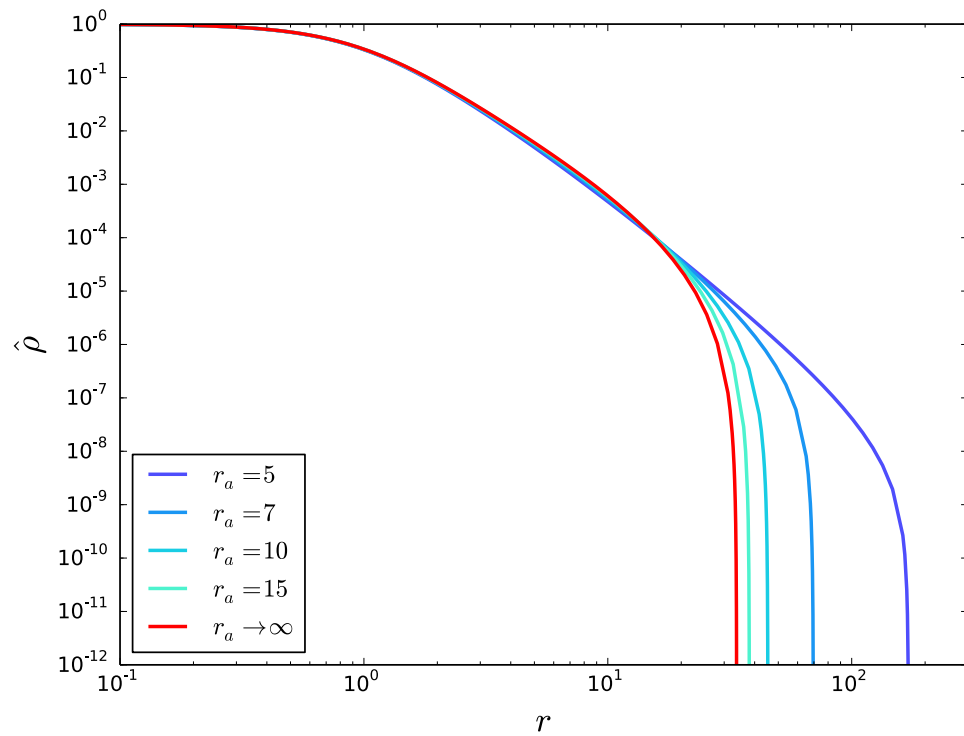
$$\hat{\phi}_0 = 7, r_a \rightarrow \infty$$



LIMEPY

Some properties of the models: the role of r_a

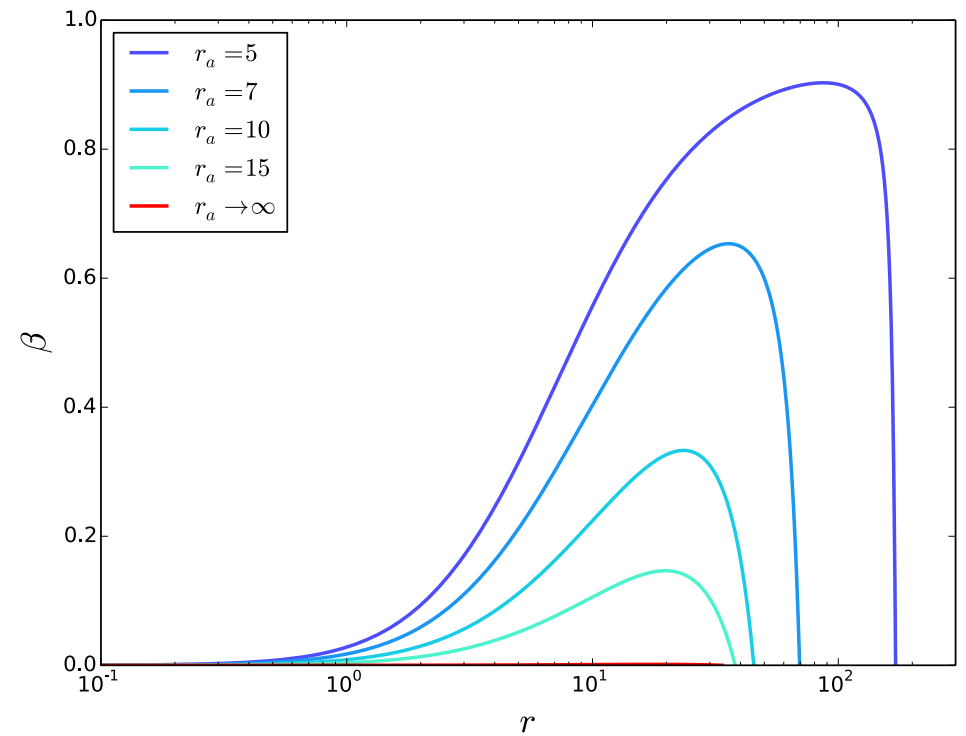
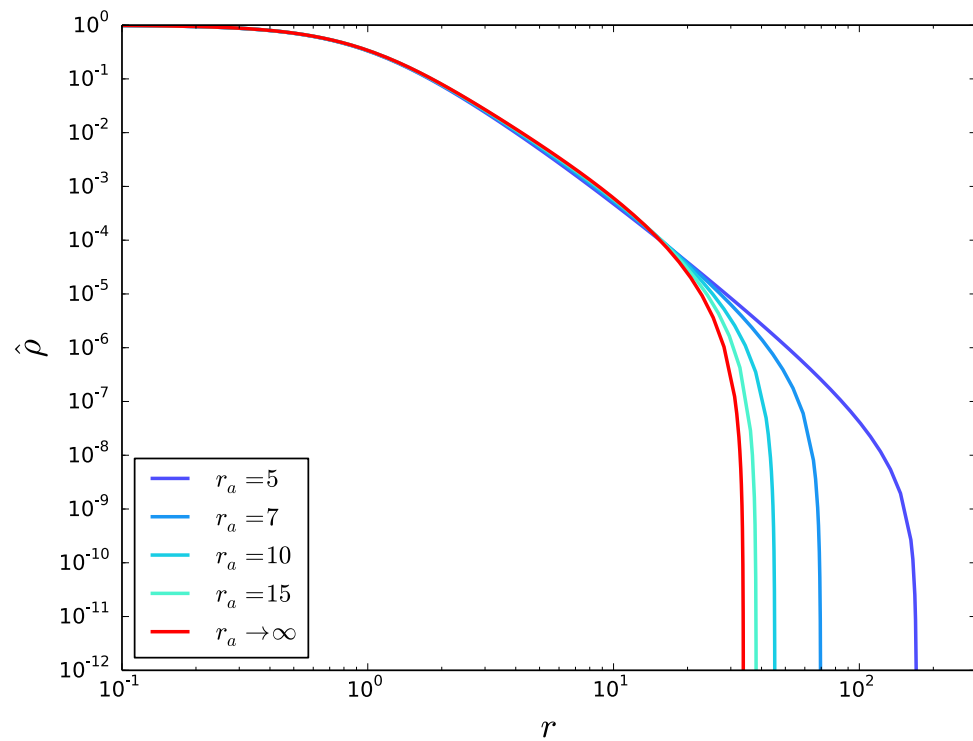
$$\hat{\phi}_0 = 7, g = 1$$



LIMEPY

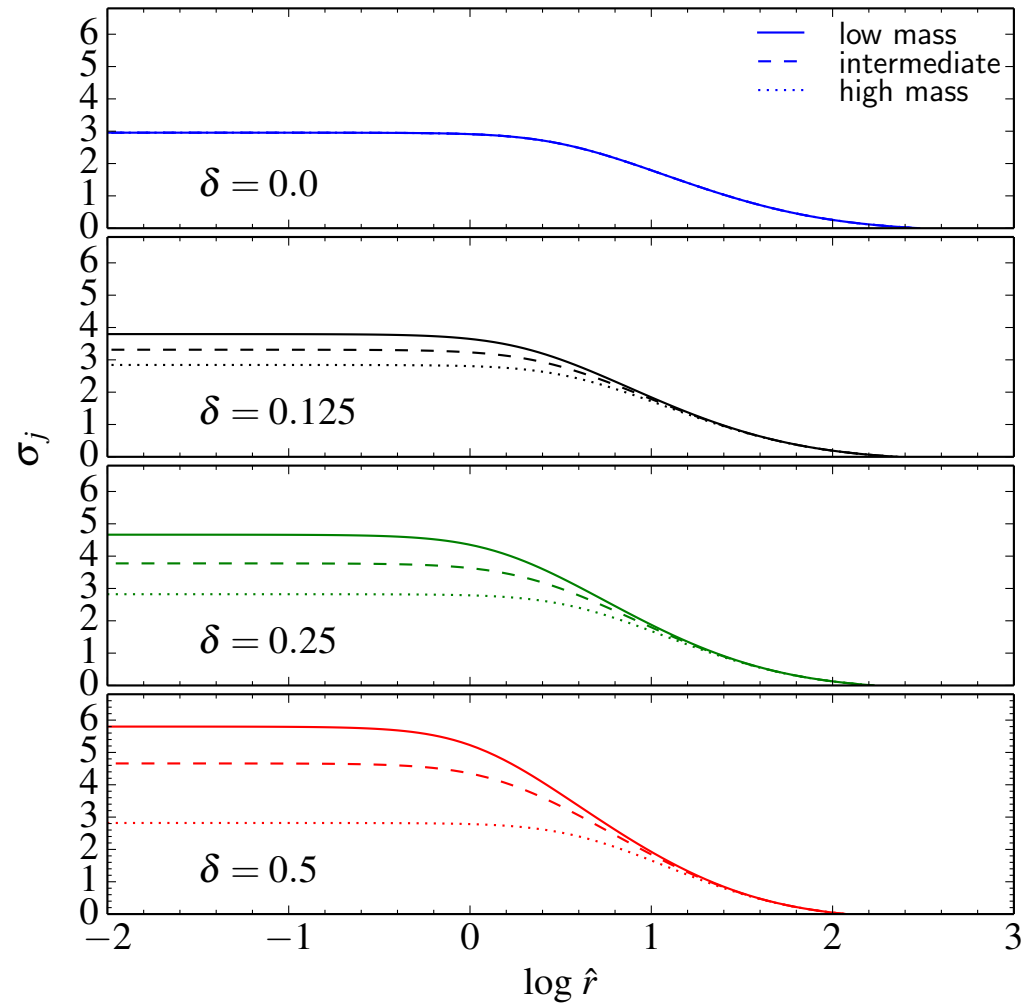
Some properties of the models: the role of r_a

$$\hat{\phi}_0 = 7, g = 1$$



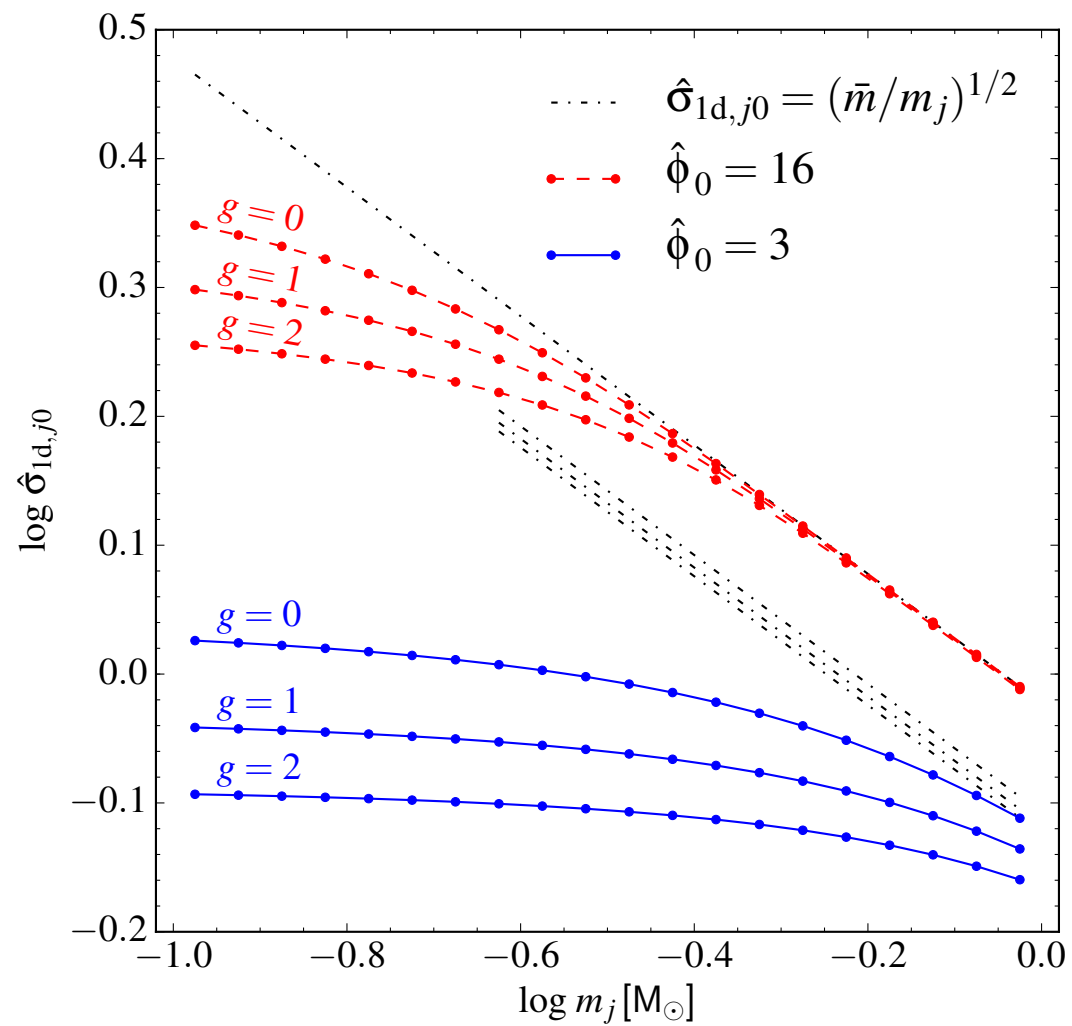
LIMEPY: Multi-mass

Some properties of the models: the role of δ



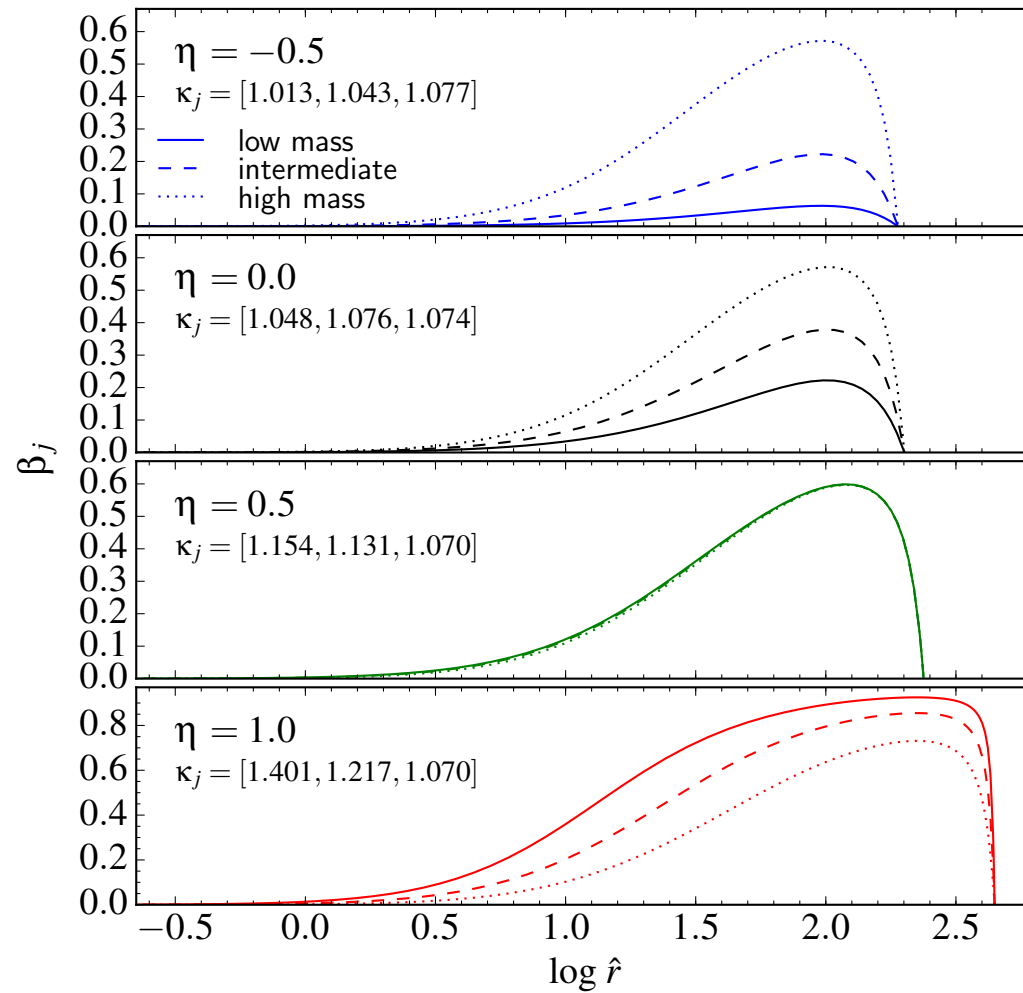
LIMEPY: Multi-mass

Some properties of the models: the role of δ

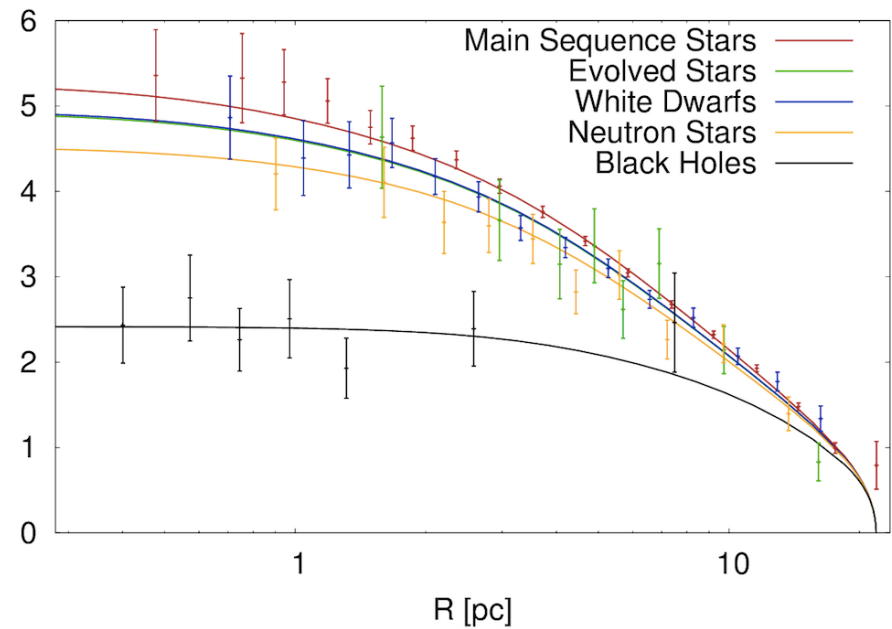
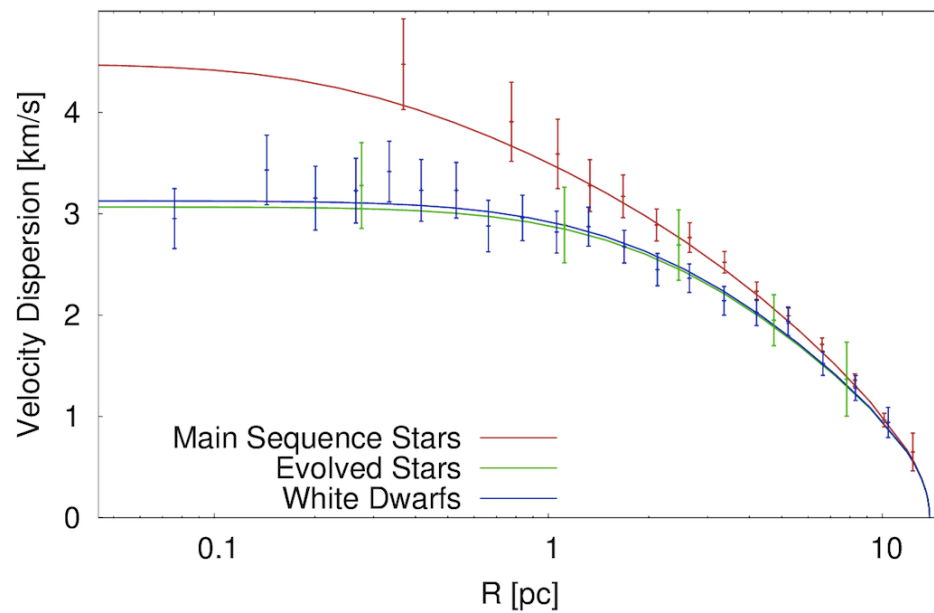
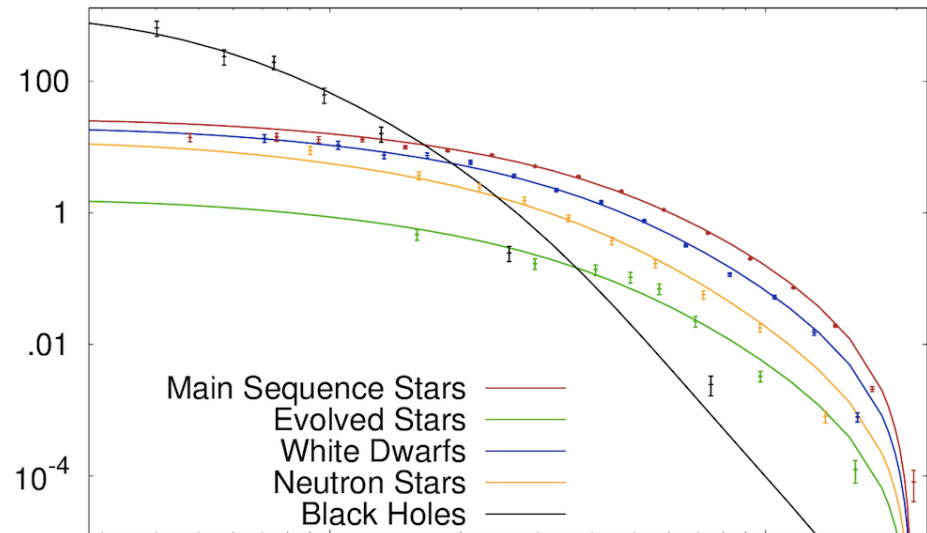
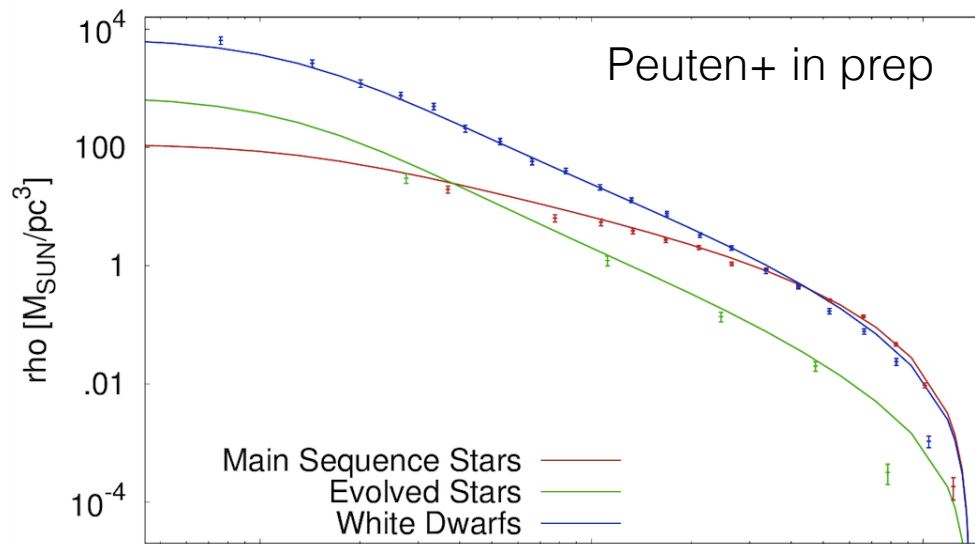


LIMEPY: Multi-mass

Some properties of the models: the role of η

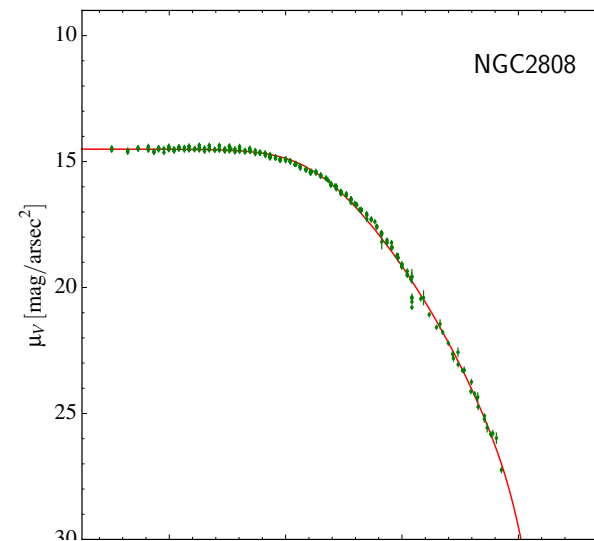
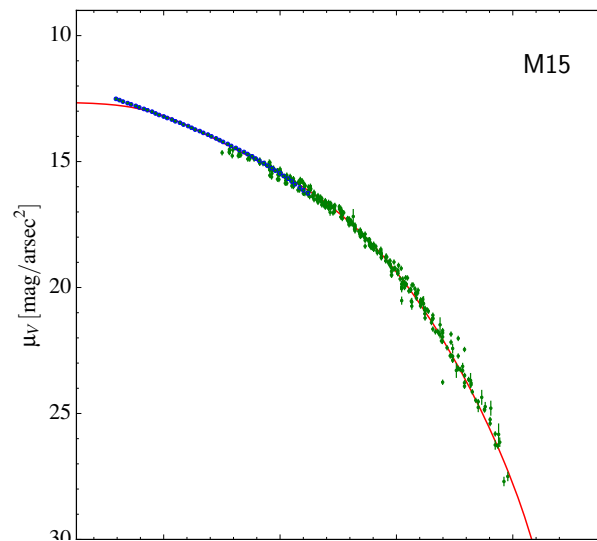


Application: Challenge 2

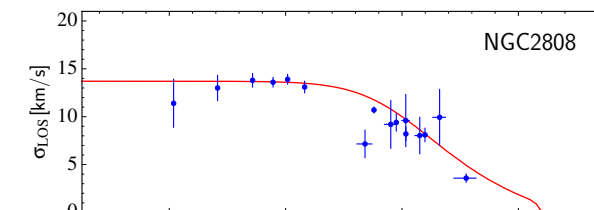
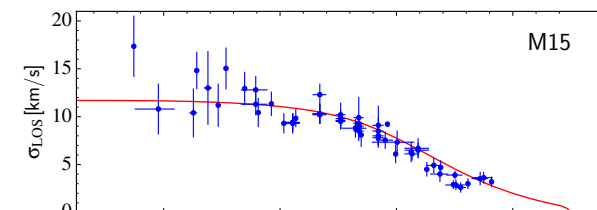


Application: M15 + NGC2808

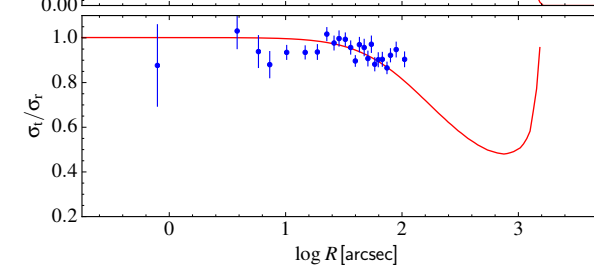
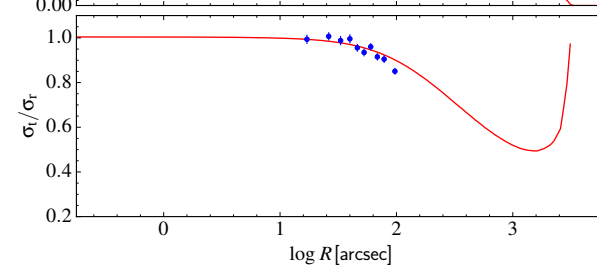
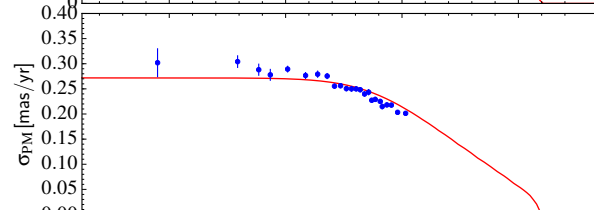
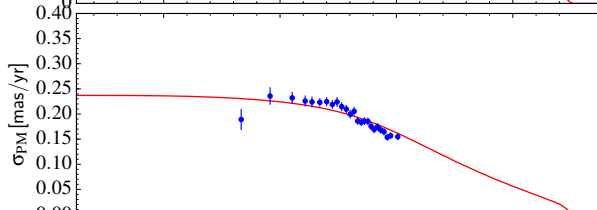
Surface brightness:



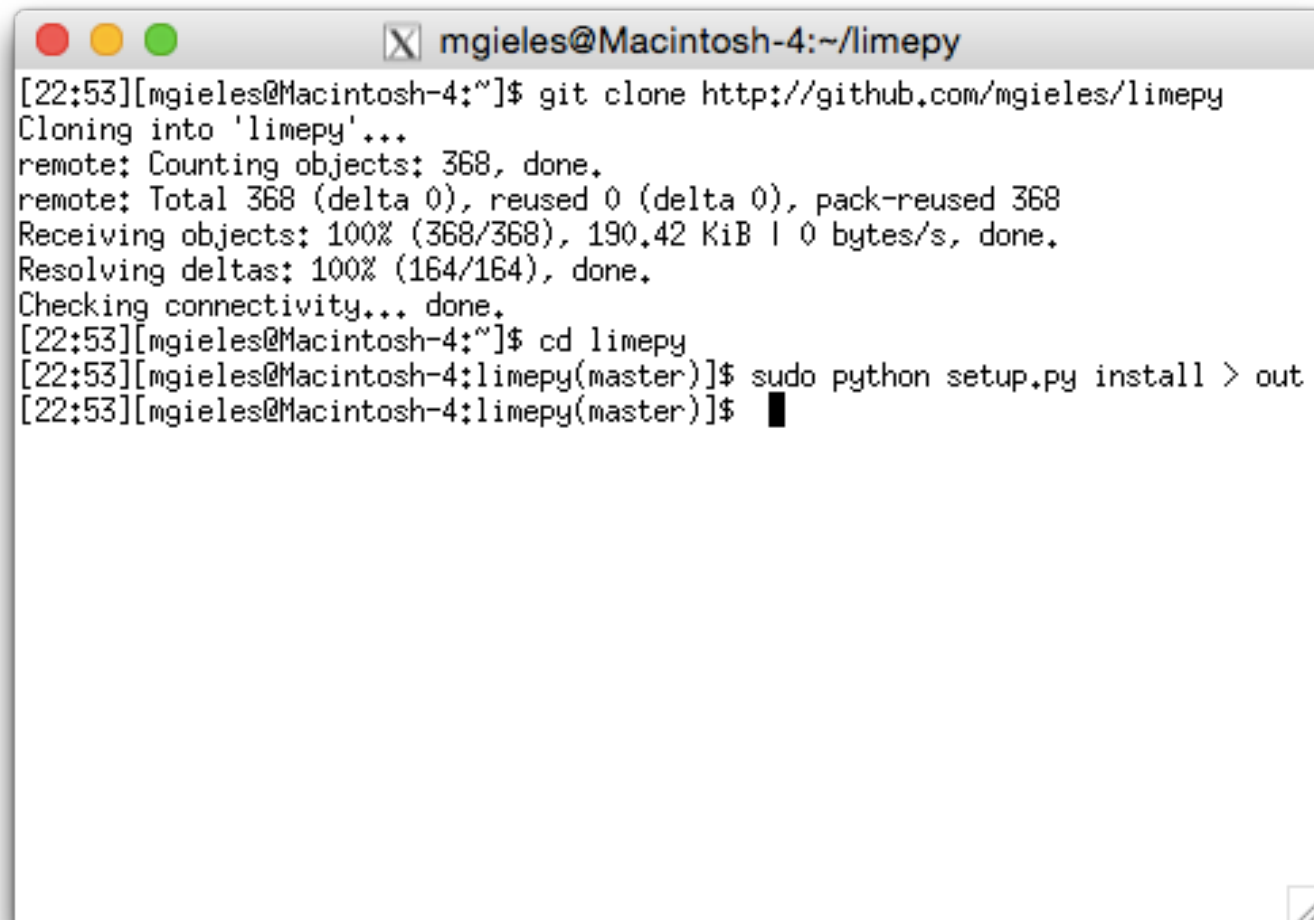
Radial velocities:



Proper motions



Install



```
mgieles@Macintosh-4:~/limepy
[22:53][mgieles@Macintosh-4:~]$ git clone http://github.com/mgieles/limepy
Cloning into 'limepy'...
remote: Counting objects: 368, done.
remote: Total 368 (delta 0), reused 0 (delta 0), pack-reused 368
Receiving objects: 100% (368/368), 190.42 KiB | 0 bytes/s, done.
Resolving deltas: 100% (164/164), done.
Checking connectivity... done.
[22:53][mgieles@Macintosh-4:~]$ cd limepy
[22:53][mgieles@Macintosh-4:limepy(master)]$ sudo python setup.py install > out
[22:53][mgieles@Macintosh-4:limepy(master)]$ █
```

>>> help(limepy)

```
mgieles@ub246072:~
Help on class limepy in module limepy.limepy:

class limepy
| Methods defined here:
|
|  __init__(self, phi0, g, **kwargs)
|      (MM, A) LIMEPY
|
|      (Multi-Mass, Anisotropic) Lowered Isothermal Model Explorer in Python
|
|      This code solves the models presented in Gieles & Zocchi 2015 (GZ15),
|      and calculates radial profiles for some useful quantities. The models
|      are defined by the distribution function (DF) of equation (1) in GZ15.
|
|      Model parameters:
|      =====
|
|      phi0 : scalar, required
|          Central dimensionless potential
|      g : scalar, required
|          Order of truncation (0<= g < 3.5: 0=Woolley, 1=King, 2=Wilson)
|
|      ra : scalar, required for anisotropic models
|          Anisotropy radius; default=1e8
|      mj : list, required for multi-mass system
|          Mean mass of each component; default=None
|      Mj : list, required for multi-mass system
|          Total mass of each component; default=None
|      delta : scalar, optional
|          Index in s_j = s x mu_j^-delta; default=0.5
|          See equation (24) in GZ15
|      eta : scalar, optional
|          Index in ra_j = ra x mu_j^eta; default=0
|          See equation (25) in GZ15
|
|      Input for scaling:
|      =====
|
|      scale : bool, optional
|          Scale model to desired G=GS, M=MS, R=RS; default=False
|      MS : scalar, optional
|          Final scaled mass; default=10^5 [Msun]
|      RS : scalar, optional
|          Final scaled radius, half-mass or virial (see below); default=3 [pc]
|      GS : scalar, optional
|          Final scaled gravitational const; default=0.004302 [(km/s)^2 pc/Msun]
|      scale_radius : str, optional
|          Radius to scale ['rv' or 'rh']; default='rh'
|
|      Options:
|      =====
|
|      project : bool, optional
|          Compute model properties in projection; default=False
|      potonly : bool, optional
|          Fast solution by solving potential only; default=False
|      max_step : scalar, optional
|          Maximum step size for ode output; default=1e10
|      verbose : bool, optional
|          Print diagnostics; default=False
|      ode_atol : absolute tolerance parameter for ode solver; default=1e-7
|      ode_rtol : relative tolerance parameter for ode solver; default=1e-7
```

```
mgieles@ub246072:~
Output variables:
=====

All models:
-----
rhat, phihat, rhoat : radius, potential and density in model units
r, phi, rho : as above, in scaled units (if scale=True)
v2, v2r, v2t : total, radial and tangential mean-square velocity
beta : anisotropy profile (equation 32, GZ15)
mc : enclosed mass profile
r0, rh, rv, rt : radii (King, half-mass, virial, truncation)
K, Kr, Kt : kinetic energy: total, radial, tangential
U, Q : potential energy, virial ratio
A : constant in DF (equation 1, GZ15)
volume : phase-space volume occupied by model
nstep : number of integration steps (depends on ode_rtol & ode_atol)
converged : bool flag to indicate whether model was solved

Projected models:
-----
Sigma : surface (mass) density
v2z : line-of-sight mean-square velocity
v2R, v2T : radial and tangential component of mean-square velocity
on plane of the sky

Multi-mass models:
-----
Properties of each component:
phi0j : dimensionless central potential
rhoatj : dimensionless density
rhoj : density profile
v2j : mean-square velocity profile
v2rj, v2tj : radial and tangential component of mean-square velocity
profile
r0j, raj : radii (King, anisotropy)
Kj : kinetic energy
Kraj, Ktj : radial/tangential component of kinetic energy

Projected multi-mass models:
-----
Properties of each component:
Sigmaaj : surface (mass) density
v2zj : line-of-sight mean-square velocity profile
v2Rj, v2Tj : radial and tangential component on the plane of the sky
of the mean-square velocity profile

Examples:
=====
Construct a Woolley model with phi0 = 7 and print r_t/r_0 and r_v/r_h

>>> k = limepy(7, 0)
>>> print k.rt/k.r0, k.rv/k.rh
>>> 19.1293426415 1.17783663028

Construct a Michie-King model and print ratio of anisotropy radius over
half-mass radius and the Polyachenko & Shukhman (1981) anisotropy
parameter

>>> a = limepy(7, 1, ra=5)
>>> print a.ra/a.rh, 2*a.Kr/a.Kt
>>> 1.03377960149 1.36280949341
```

```
mgieles@ub246072:~
v2rj, v2tj : radial and tangential component of mean-square velocity
profile
r0j, raj : radii (King, anisotropy)
Kj : kinetic energy
Kraj, Ktj : radial/tangential component of kinetic energy

Projected multi-mass models:
-----
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>>> 1.03377960149 1.36280949341

Create a Wilson model with phi0 = 12 in Henon/N-body units: G = M =
r_v = 1 and print the normalisation constant A of the DF and the
value of the DF in the centre:

>>> w = limepy(12, 2, scale=True, GS=1, MS=1, RS=1, scale_radius='rv')
>>> print w.A, w.df(0.0)
>>> [ 0.00800902] [ 1303.40270676]

Multi-mass model in physical units with r_h = 3 pc and M = 10^5 M_sun
and print central densities of each bin over the total central density
and the half-mass radius + half-mass radius in projection

>>> m = limepy(7, 1, mj=[0.3,1.5], Mj=[9.3,1], scale=True, project=True)
>>> print m.alpha, m.rh, m.rhp
>>> [ 0.30721416 0.14103549 0.55175035] 3.0 2.25494426759

df(self, *arg)
Returns the value of the normalised DF at a given position in phase
space, can only be called after solving Poisson's equation

Arguments can be:
- r, v (isotropic single-mass models)
- r, v, j (isotropic multi-mass models)
- r, v, theta, j (anisotropic models)
- x, y, z, vx, vy, vz, j (all models)

Here j specifies the mass bin, j=0 for single mass
Works with scalar and array input

interp_phi(self, r)
Returns interpolated potential at r, works on scalar and arrays
```

(END)

Plot

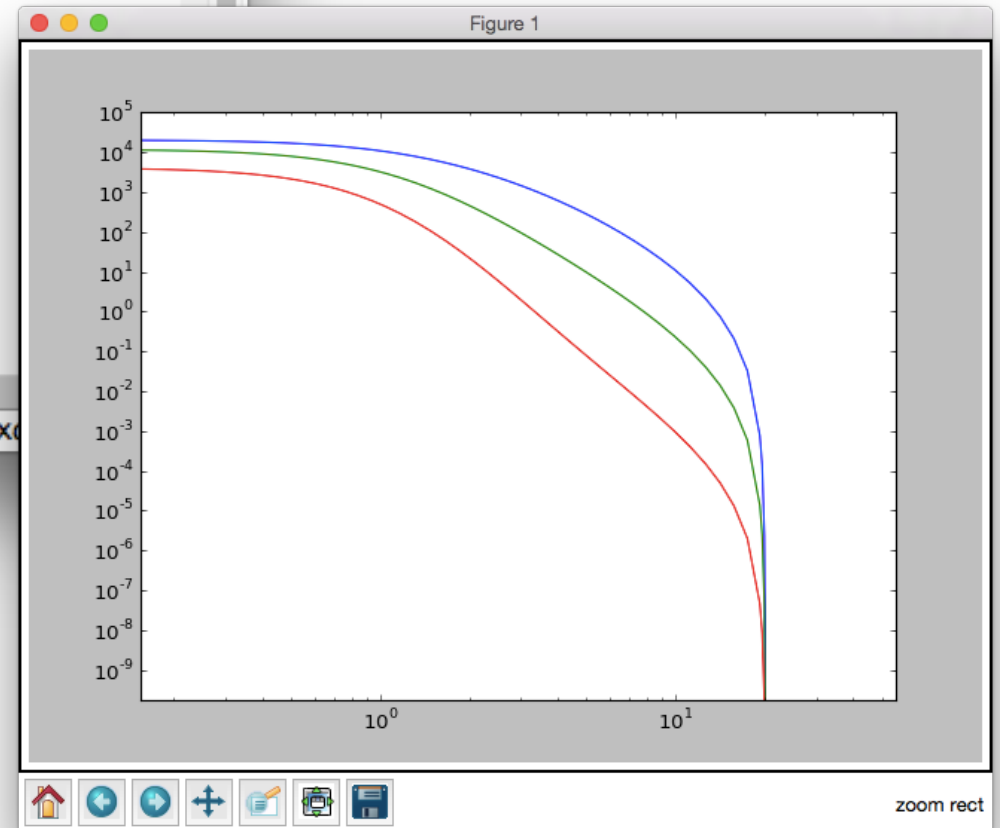
```
examplep.py
from __future__ import division
from limepy import limepy
import matplotlib.pyplot as plt

plt.ion()
plt.clf()
plt.loglog()

phi0, g, ra = 7, 1.5, 20
mj, Mj      = [0.3, 0.8, 1.3], [1, 0.1, 0.01]
M, rh      = 1e6, 3
m = limepy(phi0, g, ra=ra, mj=mj, Mj=Mj, scale=True, MS=M, RS=rh, \
           scale_radius='rh', verbose=True)

for i in range(m.nmbin):
    plt.plot(m.r, m.rhoj[i])

-:--- examplep.py All L12 (Python)
Wrote /Users/mgieles/Dropbox/projects/limepy/multi_iter/ex
```



```
>>> help(sample)
```

```
mgieles@Macintosh-4:~  
Help on class sample in module limepy.sample:  
class sample  
| Methods defined here:  
|  
| __init__(self, mod, **kwargs)  
| "  
|     Sample positions and velocities from DF generated by LIMEPY  
|  
| Parameters:  
|  
| mod : Python object  
|       Model generated by LIMEPY  
| N : scalar, optional  
|       Number of points to be generated; default=1000  
| seed : scalar, optional  
|       Random seed  
| verbose : bool, optional  
|         Print diagnostics; default=False  
(END)
```

Plot

```
from __future__ import division
from limepy import limepy, sample
import matplotlib.pyplot as plt

plt.ion()
plt.clf()

phi0, g, ra = 7, 1.5, 20
mj, Mj      = [0.3, 0.8, 1.3], [1, 0.1, 0.01]
M, rh      = 1e4, 3
m = limepy(phi0, g, ra=ra, mj=mj, Mj=Mj, scale=True, MS=M, RS=rh, \
           scale_radius='rh', verbose=True)

ic = sample(m, seed=123)

plt.plot(ic.x, ic.y, '.')
plt.plot(ic.x[ic.Nstart[2]:ic.Nend[2]], ic.y[ic.Nstart[2]:ic.Nend[2]], 'r.')
```

--:--- examplep.py All L17 (Python)

